The [ATM90E26 Datasheet](http://ww1.microchip.com/downloads/en/DeviceDoc/Atmel-46002-SE-M90E26-Datasheet.pdf) has an extensive list of calibration registers. Of these the ones we are most interested in are:

* ****Ugain**** for Voltage gain
* ****IgainL**** for Live current line gain

These also affect the checksum2 stored in the device and have to be updated together. The library provides a CalcCheckSum function to help in evaluating the checksums the ASIC needs when the gain values are changed.

## **Calibration procedure**

## **Calibrating voltage gain**

This is the easiest parameter to calibrate and requires the least equipments. The steps are:

* Setup default parameters and record voltage reported by ASIC and voltage reported by a multimeter with 0.1% accuracy at the AC bus.
* Apply scaling to the ****UGain**** parameter to account for any discprepancy according to this formula.
  + UGain\_n = (Voltage Actual / Voltage Measured) \* UGain\_o where UGain\_n is the new Voltage gain and UGain\_o is the old voltage gain.

### **Calibrating current gain**

The measurement of current in an energy monitor ASIC is the most unreliable piece since current is difficult to sample directly. We are obliged to use 1 of the 2 proxies for it.

* Magnetic field around the current carrying wire(s). Magnetic fields are typically sampled using Current Clamps or Rogowski Coils.
* Voltage drop across a thermally stable low resistance shunt in the path of the current.

The current calibration requires use of the reference resistors described in the materials section.

* Wire a 12V AC source in series with the reference resistor and an ammeter.
* Clamp the live side of the wiring with the CT being used with the ASIC and note the current measurements on the ASIC and the ammeter.
* Repeat the measurements with a few different reference Nicrome resistors, taking care not to exceed the power dissipation ratings of the resistors with heatsinks on. There are typically [4R, 8R and 10R](https://au.banggood.com/100W-Watt-Power-Metal-Shell-Case-Wirewound-Resistor-p-89494.html?ID=49543&cur_warehouse=CN) resistors in the calibration kit. With 1R resistors use 9V AC as input. The Voltage reference signal to the ASIC and current into the calibration resistors can come from separate transformers (ideally the same one is used).
* Once a few actual vs measured current values are collected use an equation similar to the ****UGain**** one to compute ****IGain****.
  + IGain\_n = (Current Actual / Current Measured) \* IGain\_o where IGain\_n is the new current gain and IGain\_o is the old current gain.
  + Update Checksum as appropriate using built in [library methods](https://github.com/whatnick/ATM90E26_Arduino/blob/master/docs/Calibration_Software.md)

### **Calibrating power**

If the voltage and current multipliers are set correctly in the above steps the power for unity power factor loads should not require any additional work.

### **Calibrating power factor**

This requires use of the variable inductor or a well known inductive load. Use the motorized load (fan/fridge) to calibrate the higher set points of the power factor and change the Lphi and Nphi default values. The library currently does not implement runtime change to these values they are hardcoded in the header file. If the purely resistive load shows unity power factor no phase angle calibrations are necessary.